

Analyzing PIPEDREAM: Challenges in testing an ICS attack toolkit

Speaker

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Agenda

- Background
- PIPEDREAM Capabilities
- Hardware & Lab Setup
- Assessing the Impact
- Results from Lab Testing
- Real World Usage
- Conclusion



It's a Group Effort

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Where'd you find it?

Required Legalese

Dragos identified and analyzed PIPEDREAM's capabilities through our normal business, independent research, and collaboration with various partners in early 2022.





PIPEDREAM Components



Designed to discover, access, manipulate, and disable Schneider Electric PLCs. Can target additional hardware through CODESYS library.



Designed to scan, identify, interact, and manipulate Omron PLCs



DRAGOS

Tool for interacting with OPC UA servers. Designed to read and write node attribute data, enumerate the Server Namespace and associated Nodelds, and brute force credentials.

Windows Components



Remote operational implant to perform host reconnaissance and command-and-control.

DUSTTUNNEL



User-mode Windows executable that drops and exploits a vulnerable ASRock driver to load an unsigned driver.

LAZYCARGO

Lab Setup & Acquisition

Impacted Devices, Abused Protocols & Vulns

OMRC NX1P2 Compact Mac NX-SL3300 Safety NJ501-1300 Automa NX-ECC EtherCA NX-EIC202 Etherne NX-EIC203 Etherne S8VK Power 1S-series Serve	hine Controller Controller tion Controller T Coupler et/IP Coupler CAT Coupler Supply o Drives	Schee TM251 TM241 TM221 TM258 TM238 LMC058 Motio LMC078 Motio		eider lectric 1 PLC 1 PLC 2 PLC 8 PLC 8 PLC ion Controller ion Controller		ICS Protocols CODESYS Schneider Discovery (NetMa Modbus Omron FINS OPC UA		ls etManage)
Vulnerabilities, Exposures, and Susceptibilities	CVE-20 LAZYCARGO to load an	020-15368 0 utilizes th unsigned d	- iis CVE Iriver.		Undisc Vulnerab Schneider	closed ilities in Electric.	CVE-20 Hardcoo Omro	22-34151 ded Creds ir on devices.
			Jan Stranger					

Lab Set-up







Omron Devices

NX1P2 Controller NX-EIC202 Ethernet IP Coupler NX-ECC201 EtherCat Coupler SL3300 Safety Controller

R88D-1SN10F-ECT Servo Drive R88D-1SN01L-ECT Servo Drive R88M-1M10030S-S2 AC Servo Motor

Schneider Electric Devices

Modicon TM241 PLC (4.0.X firmware) Modicon TM251 PLC (5.0 firmware)

OPC UA (not shown)

Kepware OPC UA server Various Rockwell devices controlling a small pipeline process.

Other hardware

Phoenix Contact power supply Sixnet Industrial ethernet switch Stack light, buttons



Device Acquisition is a Pain

TM251 running 5.0, need 4.0.X

Downgrading == bricked PLC ☺

Ask the vendor

- Company attitude
- CYA, NDAs, reporting deadlines

eBay or ask a friend

Easy to purchase, stay independent

	SCHNEIDER ELECTRIC Modicon M251 PLC TM251MESE "Barely Used"
	Condition: Used "Barely Used - Tested - 100% Functional"
	Price: C \$1,199.00 Buy It Now
Ethernet 1	Add to cart
Ethernel 2 MCB 00 80 F4 94 70 F02	Best Offer: Make Offer
	♥ Add to Watchlist
MACE DO BO F4 0A 09-D1 Setypeter	Returns accepted Ships from Canada
Hover to zoom	Shipping: Calculate Located in: Woodbridge, Ontario, Canada
a stand of the second sec	Delivery: Varies
	Returns: 30 day returns Buyer pays for return shipping See details
	Payments: PayPal G Pay VISA 6



Assessing Impact & Approach

Analysis Approach

Looking at 5 malware samples in parallel

- Focus on PLCs and malware RE.
- Test on representative devices.

Analysis Process & Goals

- 1. Static analysis while waiting for hardware.
- 2. Release of initial details and mitigation advice.
- 3. Runtime analysis with PCAP collection.
- 4. Which techniques work, and on what device.
- 5. Release updated details and specific mitigation advice.
- 6. Hypothesize and test what next versions could look like.



Analysis Questions

IMPACT OF CURRENT CAPABILITY	 Does it work? Is the CODESYS implementation specific to Schneider or applicable to all CODESYSv3 devices? Does BADOMEN's Servo module work on other servos? More generally: can these tools manipulate PLC logic?
ASSESSMENT OF FUTURE CAPABILITY	 How easy is it to automate an attack? What functionality could be added with minimal research? What will it look like in 6 months?
VICTIMOLOGY	• Can we narrow down a likely target?



Lab Testing Results



Multiplatform toolkit to interact with OPC UA servers.

FORMAT: Python framework

TARGETS: OPC-UA servers

- Scan for OPC UA Servers on a local network (default: TCP/4840).
 - Port can be changed and can scan for OPC UA Servers anywhere.
- Brute force OPC UA server based on password list supplied by operator.
 - Can use a default password or compromised passwords.
- Read OPC UA structure from the server and change specific attributes.
- Better implementation of CRASHOVERRIDE OPC-DA attack methodology.



MOUSEHOLE: Remote Interaction to Attack

- MOUSEHOLE works primarily due to the open-source OPC UA library it runs on.
- Easy to get it to work and manipulate a process.
- We tested on a Kepware OPC server connected to Rockwell PLCs controlling a mock pipeline process.
- After verifying it worked, we automated an attack using MOUSEHOLE to produce a more real-world attack scenario.



MOUSEHOLE OPERATOR VIEW



MOUSEHOLE SAFE SHUTDOWN



MOUSEHOLE: Attack scenario



- Run MOUSEHOLE via CLI to gather Server and Node information for a process.
 - ns=2;s=Channel1.Device2.high pressure setpoint
 - ns=2;s=Channel1.Device2.Level_PID
 - ns=2;s=Channel1.Device2.solenoid energize
- Remove MOUSEHOLE and deploy an automated utility to manipulate those values.
 - High pressure setpoint 15 psi -> 100 psi
 - Level_PID: 80 -> 100 (pump speed)
 - Solenoid energize: True -> False (closes the valve)

MOUSEHOLE UNSAFE CONDITIONS



MOUSEHOLE: Potential Repercussions

Deadheading is when a pump operates with no flow through the pump due to a closed or blocked discharge valve.





- A modification to the PLC logic incorrectly allowed the pump to keep running outside of designated start/stop sequence with the suction and discharge valves closed.
- Slurry inside the pump became superheated.
- This resulted in pump explosion.





Framework to interact with Schneider Electric controllers via CODESYS and Modbus libraries

FORMAT: Python + Linux ELF Library

TARGETS: Schneider Electric Controllers



- Rapid scan that identifies all Schneider PLCs on the local network from a device that has already been compromised via User Datagram Protocol (UDP) multicast with a destination port of 27127.
- Brute force Schneider Electric PLC passwords using UDP port 1740.
- CODESYS denial-of-service attack to prevent network communications from reaching the PLC.
- Sever CODESYS connections, likely to facilitate either credential capture or to prep for DOS.
- 'Packet of death' attack.
- Proxy Modbus traffic through a target PLC.
- "Maintenance" actions like logging in/out, uploading/downloading files, etc.

EVILSCHOLAR: CODESYS

- CODESYS is a device management protocol used by 100s of vendors.
- Wide usage == natural target.
- Layered protocol: Services, Channel, Datagram, Block Driver layer.
- Essentially a custom TCP implementation on top of UDP with Application layer support.



EVILSCHOLAR: Lab Set Up Issues

Devices Tested: TM241, TM251



Custom CODESYS implementation is a nightmare to deal with. CODESYS is pseudo-routable Setting up lab connections == No VM with NAT or you won't receive packets

- We had a hell of a time connecting to the devices.
- In one lab, we couldn't establish any connections.
- In another lab, connecting to these devices wasn't an issue. (?!?
- We thought it was a firmware issue. (We were wrong.)



EVILSCHOLAR: Bad Assumptions



- Multiple Parts of EVILSCHOLAR's CODESYS implementation were broken, due to the developer's invalid assumptions.
- Could connect to the TM241/TM251 with no fixes <u>if the devices were on</u> <u>a network of the right size</u>.
- Once fixed, we could connect to the TM241, TM251, Raspberry Pi, and Hitachi EHV+, and start testing plugins without worrying about network sizing. (no big endian)



EVILSCHOLAR: PLCProxy Results



Originally, we thought PLCProxy worked like this.

AFTER DYNAMIC ANALYSIS

- Original finding that it creates a route to gateway IP was incorrect.
 - 1. What it does is create a route to the internal network where gateway is located.
 - 2. The target network cannot be on the same network as the malware.
- While the proxy plugin only uses Modbus, it turns out that the TM251 will route any protocol it receives (SSH, HTTP, etc.).

EVILSCHOLAR: Logic Corruption

- EVILSCHOLAR allows an operator to transfer files to the device.
 - Pull logic, modify it, and put it back on the controller.
- This should be trivial provided the logic compiles to native assembly, and not an unknown bytecode.



SE Logic Corruption Result





SE Logic Corruption Takeaways

- We can crash and manipulate logic on the controller, creating various error and output states.
- In both cases, comms to the controller from the EWS are not possible without a power cycle.
- If you connect to the PLC before the crash, or before the code starts, the PLC won't let you retrieve the logic, only let you overwrite it. (EVILSCHOLAR can though!)
- Outputs are <u>not</u> asserted to 'FAIL SAFE' values <u>if the crash is triggered on the *first* execution cycle</u>.

Wait where are the deets?

- Reported the vulnerabilities to Schneider Electric and CODESYS Group on June 22.
- Following responsible disclosure process.
- Waiting on CVEs.





Remote shell to interact with Omron controllers via Omron HTTP API and FINS protocol

> FORMAT: Python framework



DRAGO

- Log into a PLC with a variety of methods.
- Exploit telnet connections to the PLC to load a malware implant.
- List directories of the PLC.
- Upload, download, delete and execute files on the PLC.
- Denial-of-service (DoS) attack against a PLC.
- Terminate active PLC connections.
- Scan and identify Omron devices using FINS (Factory Interface Network Service) protocol.
- Interpret Omron device responses.
- Collect PCAP on the OT network via uploaded TCPDUMP.
- Manipulate Servos via EtherCat.
- Creating, restoring, and decoding of system process and configuration files (possible ladder logic theft).
- Change Operating Mode (Program -> Run).
- Wipe the controller's memory.

BADOMEN: Console

- Console takes advantage of CVE-2022-34151(Hard-coded Credentials) to interact with an HTTP Server on the NX1P2 and other NJ-series devices
- The server has various CGI endpoints (also used by SYSMAC studio) to manipulate and administer the device: "cpu.fcgi" and "ecat.fcgi"

POST /cgi-bin/cpu.fcgi HTTP/1.1
Authorization: Digest username='',realm="CPU-Unit Interface",nonce="@,uri="/cgi-bin/
cpu.fcgi", cnonce="""", nc=00000a59, qop="auth", response="""", nc=00000a59, qop="auth", response="""", nc=00000a59, qop=""", nc=00000a59, qop="", nc=00000a59, qop=""", nc=00000a59, qop="", nc=00000", nc=00000", nc=00000", nc=00000", nc=00000", nc=0000", nc=0000", nc=000", nc=0000", nc=000", nc=000", nc=000", nc=000", nc=000", nc=00",
Host: 192.168.56.17
Cookie: ID=1585757116
Content-Length: 14319
File_download 44f4c5794ef4d2683de1c96754ebc97845f8f55874d5ae6d64cbec,2489D786231DB9289831DC235BC8BC06 .,.++5o6`(
\$.GvggJ='.>x.2/u,.YkZH~.?x>Hmxy.B>50. @2.P!>lK^
eOH^awrn.z1tkQ.e.a <p?pdyr.i}l ^&ycfft.bn.="">7K>,J</p?pdyr.i}l>
EP.~dRdT.YgIk.>`.D3Gg'h&.}"UO=m.!m
SVSMAC logic transfer

BADOMEN: Logic Corruption

Backup & Transfer modules allow for retrieving & repackaging new logic.

Test:

- 1. Use the Backup Module to retrieve logic.
- 2. Identify binary shared object and disassemble.
- 3. Change entrypoint function code with a branch to a bad address.
- 4. Repackage code.
- 5. Use Transfer Module to replace files on the controller.



Results – Major Fault

Level		Source	Source Details	Event Name	Event Code
🔒 Major fa	ajor fault PLC			PLC Function Processing Error	0x40110000
Major fault PLC			Task Execution Timeout	0x60020000	
Details A fatal error was detected in the PLC Function Module. [Cause] An error occurred in the software. [Attached information 1] System information [Attached Information 2] System information [Attached information 3] System information [Attached information 4] System information		n the PLC Function Module.	Task execution exceeded the timeout detection time. [Cause] (1) The timeout detection time setting is too short. (2) The task period setting is too short. (3) A user program is too large. (4) The number of times that processing is repeated is (5) Task Priority Error (6) Frequent Event Task Execution [Attached Information 1] Name of task where error occurred.	larger than expected.	
Attached information 1	PRG:Prog	ram0			



Attached information 1

Program Upload Fails

This also prevents the engineer from enabling Program Mode

Transfer from Controller	
The following data will be transferre	d.
- Configurations and Setup EtherCAT, CPU Rack, I/O Map, C Motion Control Setup, Task Settings	ontroller Setup from Controller
- Programming There POUs, Data, Library Proce	e are no data to transfer. ess was aborted.
Options Do not transfer the following. - NX Unit application data on - Unit operation settings and I Do not transfer the EtherNet/I	OK (All items are not transferred.) the CPU Rack and EtherCAT slave backup parameters. NX Unit application data on Slave Terminals. P connection settings (i.e., tag data link settings).



BADOMEN: Logic Corruption Confirmed

- Recovery?
 - Restore from SD Card fails, but allows you to enable Program mode
 - Then, factory reset.
 - Finally, you can restore logic to controller.
- Still under investigation:
 - Other methods of recovery.
 - What our code modification did to the controller.



BADOMEN: Servo Module Testing

Devices Tested: NX1P2, R88D-1SN10F-ECT & R88D-1SN01L-ECT Servo Drives, & R88M-1M10030S-S2 AC Servo Motor



- BADOMEN has a Servo Module for reading and writing Servo Drive parameters via EtherCat.
- Servo Motor spins a shaft.
- Servo Drive powers the motor, controls the motor, handles comms to the master PLC.
- 1SN10F is a 380VAC to 480VAC drive. 1SN01L is a 100-120VAC Drive.
- Verified that comms worked with the large drive, then switched to the small one.
 - No access to reliable source of three phase 480VAC
 - Using 120VAC greatly reduces risk of accidental electrocutions or arcing







ETHERCAT SETUP



BADOMEN: Troublesome Parameters

We disabled the following parameters: Excessive Velocity Deviation Detection (3B60.05) Warning Mask 1 selection (4020.01) Warning Mask 3 selection (4020.03) Position Detection Function -Following Error (3B50.05)

We manipulated these: Set to 1 stops the servo Excessive Speed Detection (3B60.04) - Set to max means 1.2x max speed Set Vibration Detection (3B70.01) - Set this to max 500%



BADOMEN: Servo Logic Manipulation

- Manipulating Parameters is interesting and likely more of a precursor to an attack.
 - Although spamming Excessive Speed Detection would be a bad day.
- The NX1P2 stores the program that controls the servo drive.
- We already know we can modify code on the device.
- Can we modify code that controls the Servo's RPM?



Step 1: Download Logic to the Device

Step 0: Watch YouTube video on setting up Servo





Step 2: Grab Backup and Decompile

Function name	Segment	Start	Length	Locals
	.plt	00000548	0000000	
F LPOU_NX_Get1sClk	.plt	00000554	000000C	
🗾 start	.text	00000560	0000008	
<u></u> f_sub_568	.text	00000568	00000014	
<u></u> <i>f</i> sub_57C	.text	0000057C	0000018C	00000028
<u> </u>	extern	00001DD <mark>4</mark>	00000004	
<u>f</u> imp_LPOU_NX_Get1sClk	extern	00001DD8	00000004	

Step 3: Patch args Step 4: Transfer to PLC

*(_	_BYTE *)(v17 + 16) =	= 0;				
//	Parameter settings	before	calling	function	block	
//	Distance,					
//	Velocity					
11	Acceleration					

>>>
>>> from ieee754 import IEEE754
>>> conv = lambda x: print(IEEE754(x).str2hex())
>>> conv(120.0)
405e00000000000
>>> conv(40.0)
40440000000000

// It appears that it may hvae just compiled it in order.

// Numbers are represented as IEE754 floats

**(_WORD **)(v16 + 8) = v14;

*(_QWORD *)*(_DWORD *)(v16 + 16) = 0x405E00000000000LL;// 120 units, one of distance, acceleration or deceleration
v18 = *(_DWORD **)(v16 + 24);

v18[1] = 0x40440000;

*v18 = 0;

// Deceleration

*(_QWORD *)*(_DWORD *)(v16 + 32) = 0x405E0000000000LL;// 120 units, one of distance, acceleration or deceleration
*(_QWORD *)*(_DWORD *)(v16 + 40) = 0x405E000000000LL;// 120 units, one of distance, acceleration or deceleration
result = POU_runFUNCTION_BLOCK();



BADOMEN MAX VELOCITY



BADOMEN: Safety System Corruption

- Even from the UI, it was clear that safety programming was a very separate process:
 - Doesn't transfer logic the same way.
 - Put the controller in program mode, then debug stop. This transfers logic.
 - Then transition to Debug Run, followed by a Safety Validation.
 - Finally, the safety controller can enter run mode.



BADOMEN: Safety Program Download



Safety Function



STSMAC Safety Flogram Downloa



BADOMEN: No support for Safety Programs

- BADOMEN only supports the CPU and ECAT endpoints.
- Safety Programming uses the NxBus endpoint.
- There are no references to this endpoint in BADOMEN.
- This is likely the next step development-wise for a full-fledged attack against a Servo.
- (Unless the network is poorly configured.)



Real World Usage

- These utilities can cause problems now.
- But in our judgement, usage would look a lot like our MOUSEHOLE demo
 - IT intrusion to steal important process documentation
 - Use PIPEDREAM to recon plant network and find important PLCs that control key aspects of the target process
 - Use this knowledge to develop automated attack utilities to achieve a disruptive/destructive effect.





PIPEDREAM is a new escalation in mal dev

- First time we've seen malware devs attempt a plugin framework for specific PLCs/Protocols.
 - ICSsploit and Metasploit "SCADA" aren't quite the same.
- ICS process agnostic.
- Enables an operator to conduct recon and disruption.





Industry Improvements

- Open up Protocols and Operating Systems.
 - We're so behind vs IT Software and Internet Protocols.
- EWS or separate vendor distributed utilities need to support forensics for IR and post-mortems.
 - The fact that SoMachine and Sysmac can't pull a bad project file is an issue.
 - Vendors aren't the only experts anymore.
- Implement better integrity checking for running code. Don't assume code always comes from the EWS!



Thank You!

For mitigations: dragos.com/pipedream

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